

# Machine Learning for Healthcare

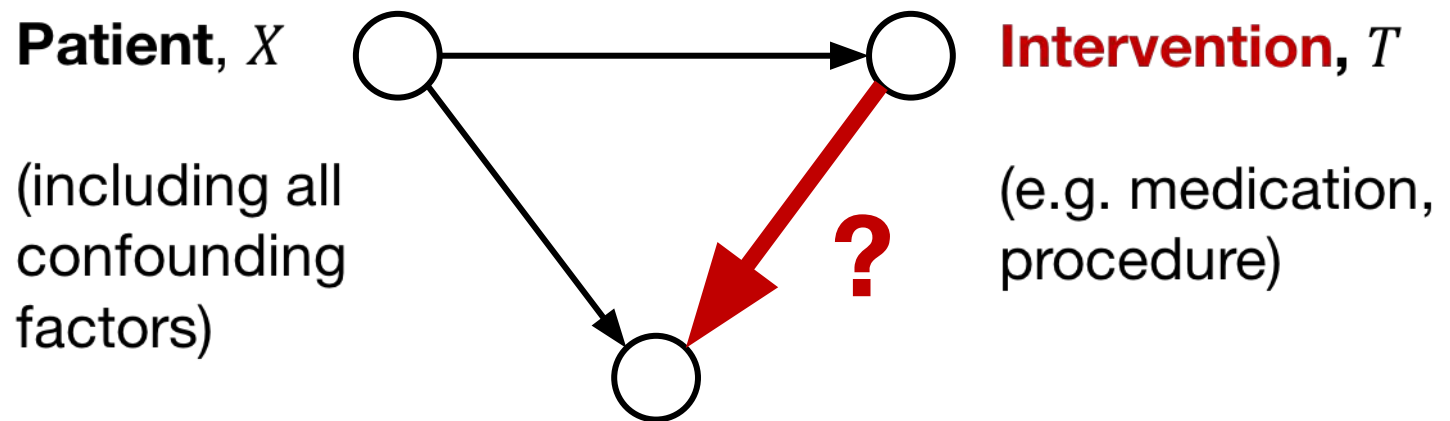
## 6.7930, HST.956

### Lecture 12: Causal Inference Part 3

David Sontag



# Reminder: Causal inference



*High dimensional*

*Observational data*

# Reminder: Causal inference

- Two approaches to use machine learning for causal inference
  - Predict outcome given features and treatment – i.e.,  $E[Y | X, T]$  – then use to impute counterfactuals (*covariate adjustment*)
  - Predict treatment using features (*propensity score*) – i.e.,  $\Pr(T | X)$  – then use to reweight outcomes

Consistency of estimates depend on:

- Causal graph being correct (i.e., no unobserved confounding)
- Identifiability of causal effect (i.e., overlap or correctly specified model)

# Same ideas can be used to evaluate *policies* using observational data

- Suppose someone gave us a policy  $\pi(l)$  that outputs  $a_1$  vs  $a_2$

Example: which antibiotic to prescribe?

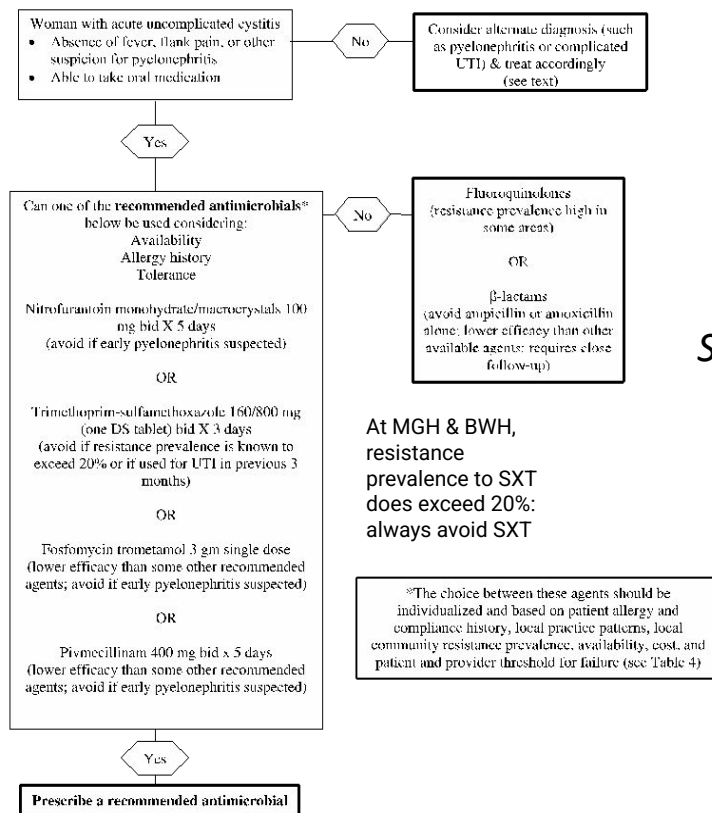


Affects 1 in 2 women during lifetime; 3rd most common cause for antibiotic treatment

# Same ideas can be used to evaluate *policies* using observational data

- Suppose someone gave us a policy  $\pi(l)$  that outputs  $a_1$  vs  $a_2$

Example: which antibiotic to prescribe?



Infectious Disease Society of America (IDSA) guidelines

Simplifies to



Resistance or exposure to NIT in past 90 days?

No

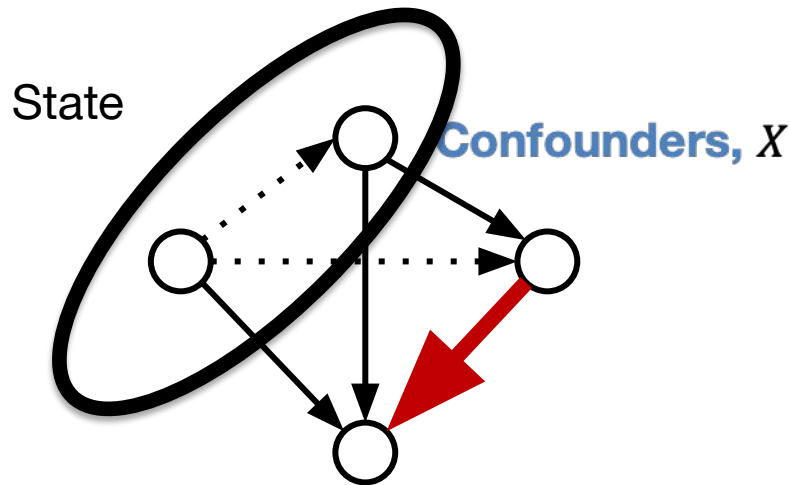
Yes

Prescribe NIT (Nitrofurantoin)

Prescribe CIP (Ciprofloxacin)

# Same ideas can be used to evaluate *policies* using observational data

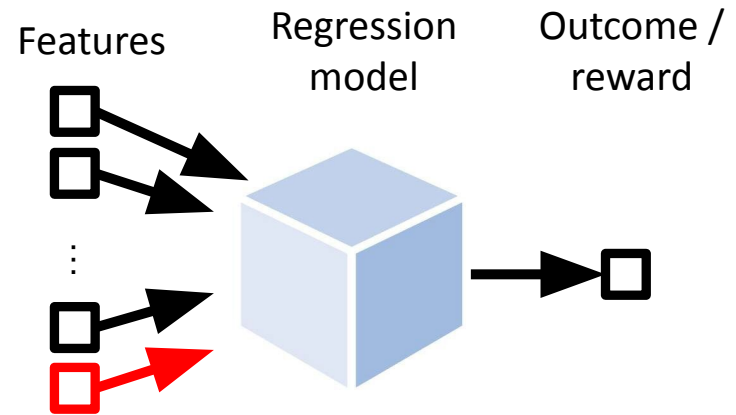
- Suppose someone gave us a policy  $\pi(l)$  that outputs  $a_1$  vs  $a_2$
- How do we evaluate it?
- We give two approaches, one based on potential outcomes and the other based on propensity scores
- In both cases, we have to first consider the causal graph that underlies the *observational data*



Switched notation to what's more typically used in RL  
action  $A$ : Treatment  $T$   
reward  $R$ : Outcome  $Y$

# Evaluating policies using potential outcomes

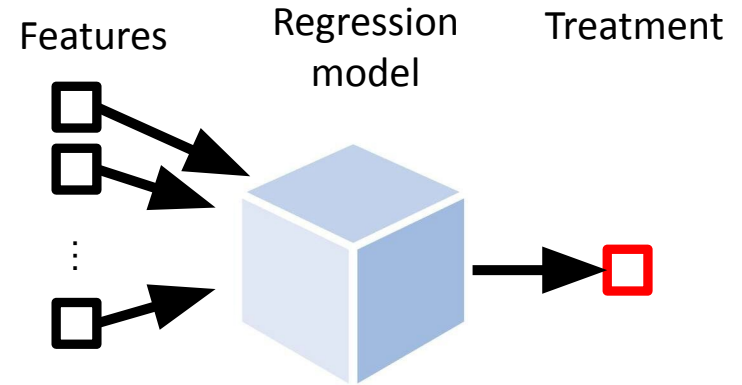
- First, use machine learning to obtain a model that can predict potential outcomes (we need ignorability, overlap)
- Then, use this model to impute policy outcomes:



$$\hat{Q}(\pi) = \frac{1}{n} \sum_{i=1}^n f(l_i, x_i, \pi(l_i))$$

# Evaluating policies using inverse propensity scores

- 



$$\hat{Q}^{IPW}(\pi) = \frac{1}{n} \sum_{i=1}^n \frac{1[a_i = \pi(l_i)]}{\hat{p}(a_i | s_i)} R_i$$

Aside: is this the right goal? What if we wanted to control worst-case reward instead of average?



# Learning policies from observational data

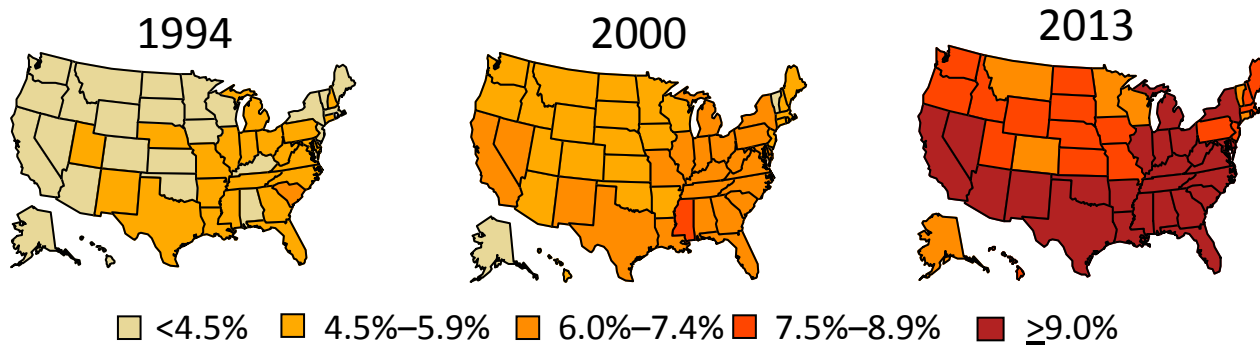
- Consider our first estimator:  $\hat{Q}(\pi) = \frac{1}{n} \sum_{i=1}^n f(l_i, x_i, \pi(l_i))$

- Create data set  $\{(l_i, o_i)\}$  where

$$o_i = \arg \max_A f(l_i, x_i, A) \quad \text{Notice relationship to CATE}$$

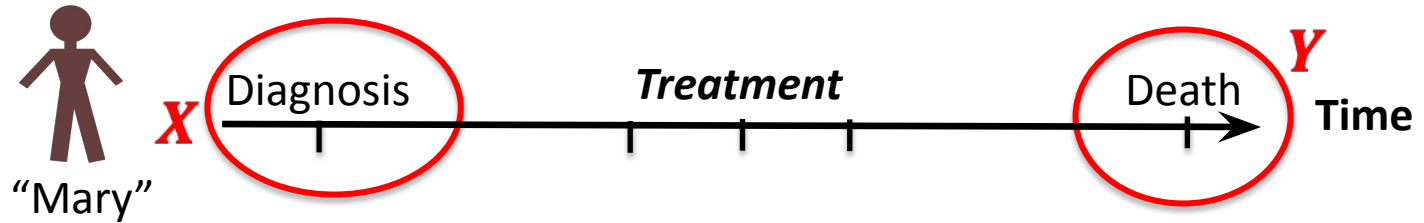
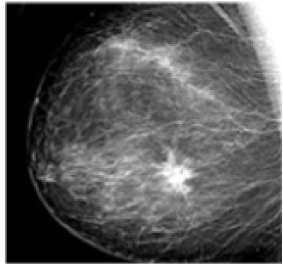
- Use an (interpretable) ML algorithm to fit this new dataset
- The resulting policy may be a much simpler function than  $f$ !

# Does gastric bypass surgery prevent onset of diabetes?



- Gastric bypass surgery is the highest negative weight (9th most predictive feature)
  - Does this mean it would be a good intervention?
- Yes, *if*....
  - Interpret ‘gastric bypass surgery’ feature as T
  - Interpret all the other features as X; assume they all include all relevant confounders and do not include anything post-treatment
  - True potential outcome function is linear

# What is the likelihood this patient, with breast cancer, will survive 5 years?



**A long survival time may be because of treatment!**

- Group into  $K$  categories of treatment strategies  $T$  (one of which might be “no treatment”)
- Gather data on confounding factors  $C$  that might influence both treatment decision and outcome
- Learn  $f(X,C,T)$  to predict  $Y$  (survival time)
- Assess overlap\* by looking at  $p(X,C|T)$  or  $p(T|X,C)$
- Predict survival under a specific treatment regime  $k$  using  $f(X,C,k)$
- Will survive 5 years when treated *optimally* if  $\max_k f(X,C, k) > 5$

\* See, e.g., Oberst, Johansson, Wei, Gao, Brat, Sontag, Varshney. Characterization of Overlap in Observational Studies, Conference on Artificial Intelligence and Statistics (AI-STATS), 2020.

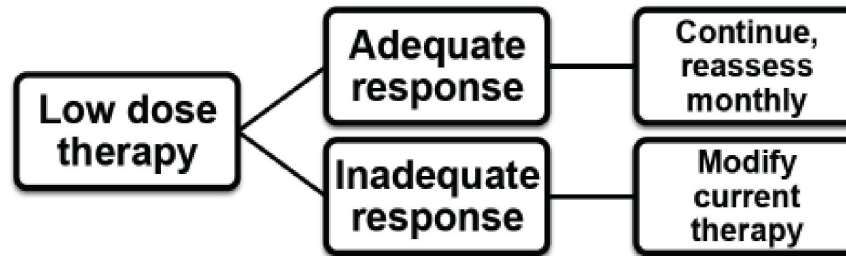
# A path to personalized medicine

- Clinical practice: Clinicians make (a series of) treatment decision(s) over the course of a patient's disease or disorder
  - Key decision points in the disease process
  - Could be a fixed schedule, a milestone in the disease process, or an event necessitating a decision
  - Several treatment options at each decision point
- Thus: treatment in practice involves **sequential decision-making** based on accruing information

# Dynamic treatment regime

- Sequential decision rules, each corresponding to a key decision point
- Each rule tells us treatment to be given from among the available options based on the accrued information on the patient to that point
- Taken together, the rules define an algorithm for making treatment decisions
- *Dynamic* because the treatment action can vary depending on the accrued information




# Example: ADHD therapy



- Decision 1: Low-dose therapy – 2 options: medication or behavior modification
- Subsequent monthly decisions:
  - Responders: Continue initial therapy
  - Non-responders – 2 options: add the other therapy or increase dose of current therapy
- Objective: maximize *end-of-school-year performance*

# Example: ADHD therapy

- This is a dynamic treatment strategy because of the decision when to stop

Point interventions	Sustained strategies	
	Static	Dynamic
		
<ol style="list-style-type: none"><li>1. Initiate treatment at baseline</li><li>2. Do not initiate treatment at baseline</li></ol>	<ol style="list-style-type: none"><li>1. Initiate treatment at baseline and continue over follow-up</li><li>2. Do not initiate treatment over follow-up</li></ol>	<ol style="list-style-type: none"><li>1. Initiate treatment at baseline and continue over follow-up, unless a contraindication occurs</li><li>2. Do not initiate treatment over follow-up, unless an indication occurs</li></ol>

(Material from Marie Davidian, *An Introduction to Dynamic Treatment Regimes*; example from Susan Murphy)

# Example: First-line treatment for multiple myeloma

- Decision 1: Induction chemotherapy (options  $C_1, C_2$ )
- Decision 2:
  - Maintenance treatment for patients who *respond* (options  $M_1, M_2$ )
  - Start a different cancer treatment for those who don't respond (options  $S_1, S_2$ )
- Objective: maximize *survival time*
- Example rules for decision 1:
  - $C_1$ : If “age < 65 and in excellent physical health”, give bortezomib, lenalidomide, dexamethasone chemotherapy followed by autologous stem cell transplant. Otherwise, treat with daratumumab, bortezomib, melphalan, & prednisone.
  - $C_2$ : treat everyone with daratumumab, bortezomib, melphalan, & prednisone

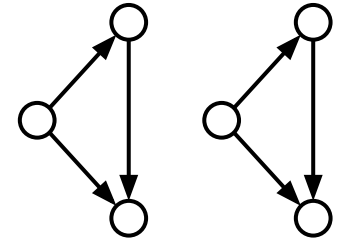


# Example: First-line treatment for multiple myeloma

- Which is the best treatment regime (policy)?
- Evaluate each of the following 8 dynamic regimes:
  1. Give  $C_1$  followed by ( $M_1$  if response,  $S_1$  if no response)
  2. Give  $C_1$  followed by ( $M_1$  if response,  $S_2$  if no response)
  3. Give  $C_1$  followed by ( $M_2$  if response,  $S_1$  if no response)
  4. Give  $C_1$  followed by ( $M_2$  if response,  $S_2$  if no response)
  5. Give  $C_2$  followed by ( $M_1$  if response,  $S_1$  if no response)
  6. Give  $C_2$  followed by ( $M_1$  if response,  $S_2$  if no response)
  7. Give  $C_2$  followed by ( $M_2$  if response,  $S_1$  if no response)
  8. Give  $C_2$  followed by ( $M_2$  if response,  $S_2$  if no response)
- Goal: evaluate the average *outcome* if all patients in the population were to follow each regime

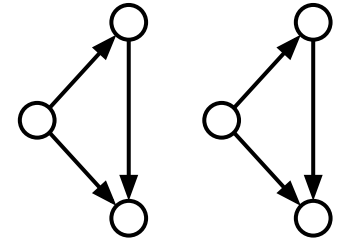
# Warm up: Evaluating dynamic treatment regimes

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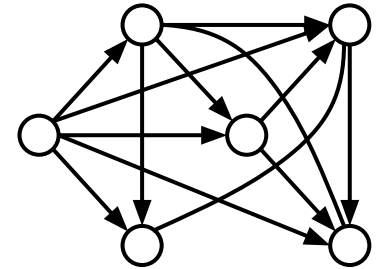
# Warm up: Evaluating dynamic treatment regimes

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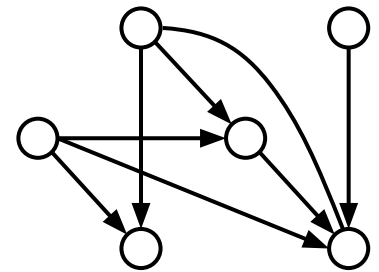
# Evaluating dynamic treatment regimes

- Notice that the same estimator *does not* make sense when, e.g.,  $S_2$  depends on  $A_1$
- The distribution of states  $S_2$  will be affected by the policy's choice of actions  $A_1$ 
  - Cannot use the observational distribution



# Evaluating dynamic treatment regimes: parametric G-formula

- ① **Fit parametric regression models** for  $Y_t$  and death at each follow-up time  $t$  as a function of treatment and covariate history among those under follow-up at time  $t$
- ② **Monte Carlo simulation** to generate a 10,000-person population under each strategy by sampling with replacement from the original study population (to estimate the standardized cumulative risk under a given strategy)
- ③ **Repeat in 500 bootstrap samples** to obtain 95% confidence intervals (CIs)



**Concern: Errors may compound; also, may be insufficient data for any one time step.**

[James Robins. A new approach to causal inference in mortality studies with a sustained exposure period—application to control of the healthy worker survivor effect. *Mathematical Modelling*, 1986.]

*For recent work, see:* Rui Li et al., G-Net: a Recurrent Network Approach to G-Computation for Counterfactual Prediction Under a Dynamic Treatment Regime. *Proceedings of Machine Learning Research* 158:282–297, 2021.]

# Many more ideas and methods

- Doubly robust estimators that combine both regression and IPW
- Natural experiments & regression discontinuity
- Instrumental variables
- Sensitivity analyses

# Many more ideas and methods – Natural experiments

- Does stress during pregnancy affect later child development?
- Confounding: genetic, mother personality, economic factors...
- Natural experiment: the Cuban missile crisis of October 1962. Many people were afraid a nuclear war is about to break out.
- Compare children who were in utero during the crisis with children from immediately before and after

# Many more ideas and methods – Instrumental variables

- Informally: a variable which affects treatment assignment but not the outcome
- Example: are private schools better than public schools? Which students would benefit the most?
- Confounding: different student population, different teacher population
- Can't force people which school to go to

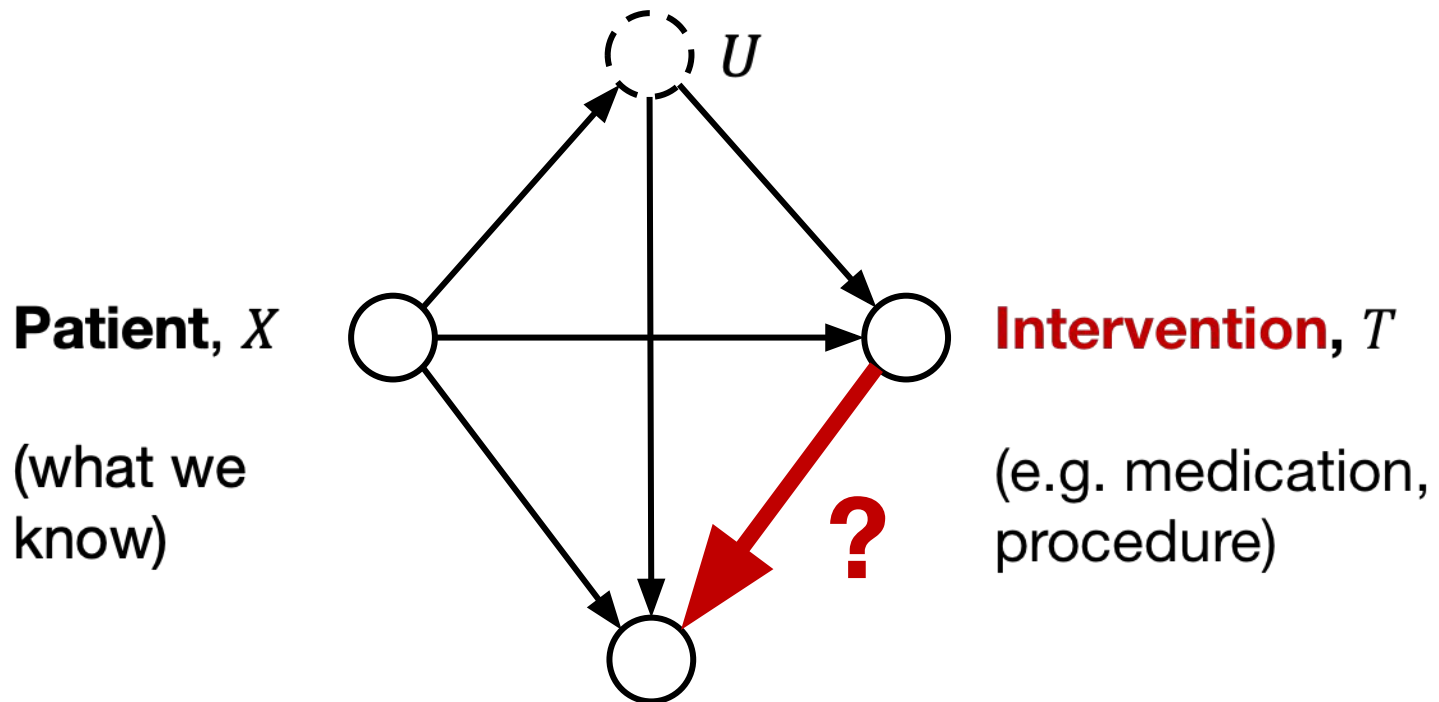


# Many more ideas and methods – Instrumental variables

- Informally: a variable which affects treatment assignment but not the outcome
- Example: are private schools better than public schools? Which students would benefit the most?
- Can't force people which school to go to
- *Can randomly give out vouchers to some children, giving them an opportunity to attend private schools*
- *The voucher assignment is the instrumental variable*

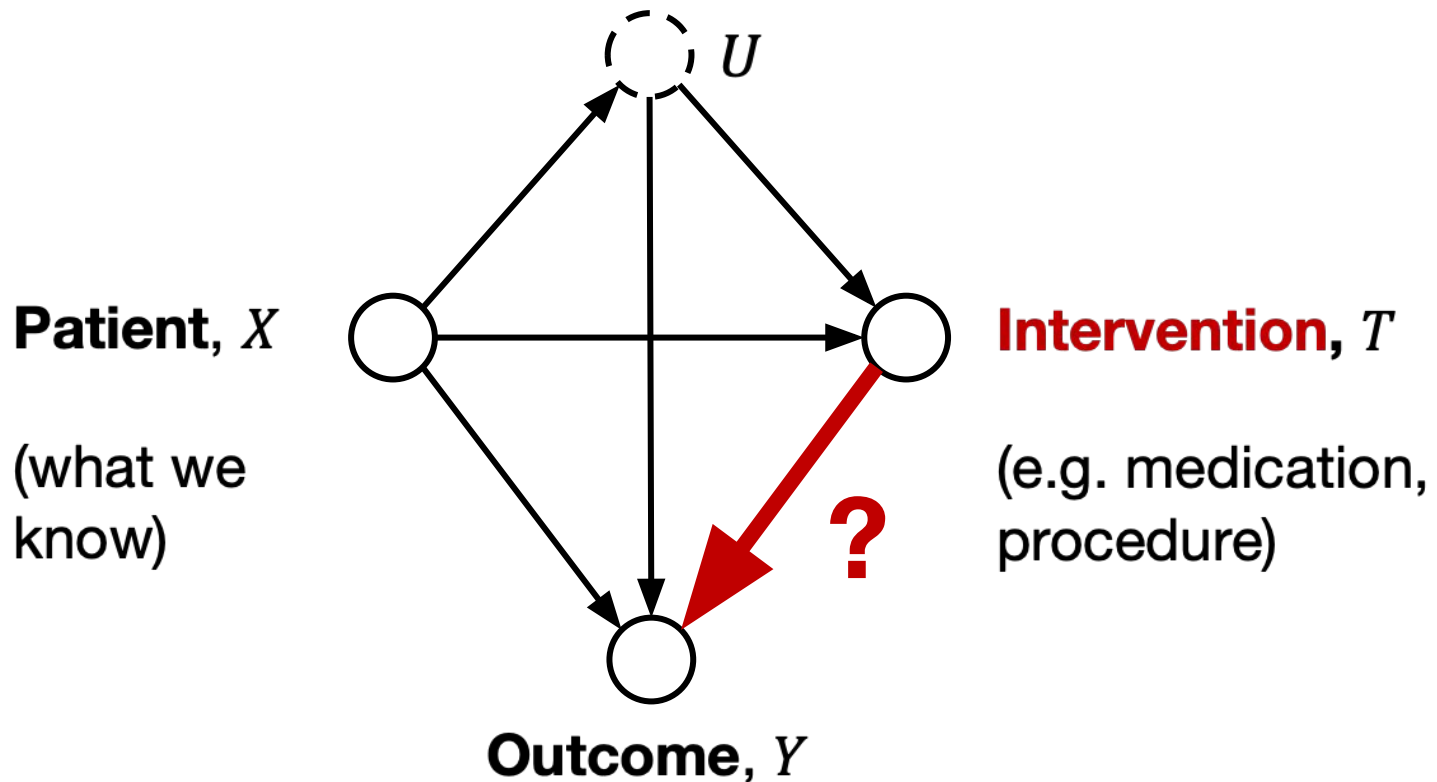
# Estimation using an instrumental variable

Goal: estimation in setting where there are unobserved confounders,  $U$ , not captured in  $X$



# Estimation using an instrumental variable

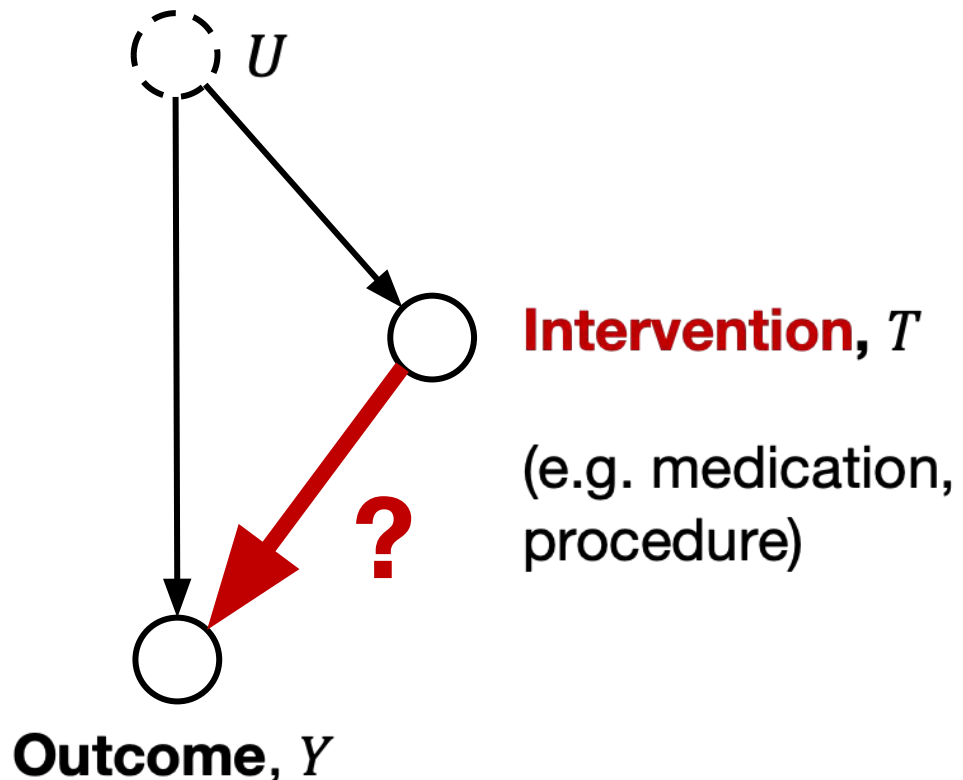
First, assume no patient covariates (with this, we will only be able to estimate ATE not CATE)



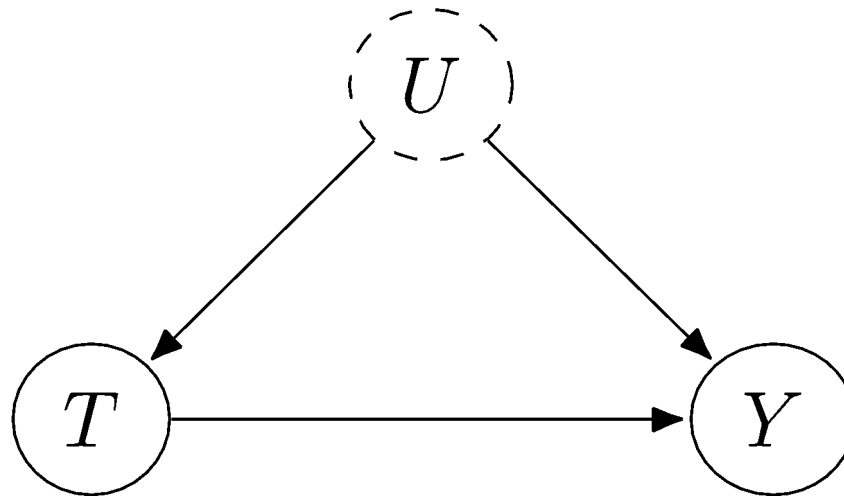
# Estimation using an instrumental variable

First, assume no patient covariates (with this, we will only be able to estimate ATE not CATE)

*Note: this is without loss of generality (since  $U$  could include all of  $X$ )*



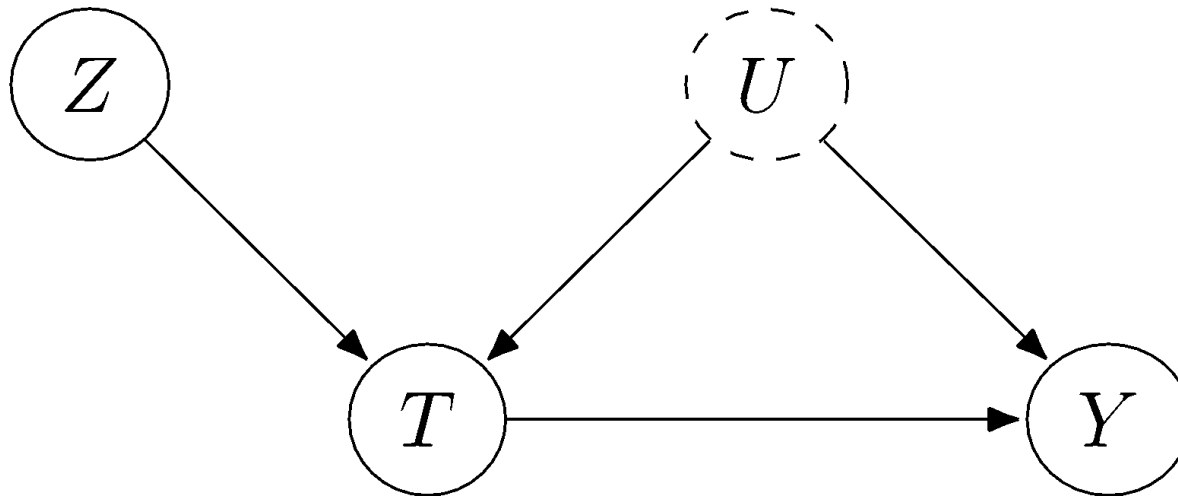
# Estimation using an instrumental variable



(Slides adapted from Brady Neal's Introduction to Causal Inference class)

# Estimation using an instrumental variable

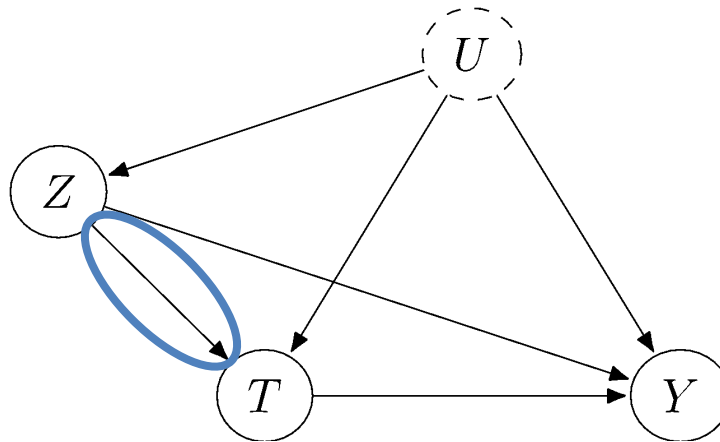
Instrument (e.g., voucher)



(Slides adapted from Brady Neal's Introduction to Causal Inference class)

# Assumption 1: Relevance

Z has a causal effect on T

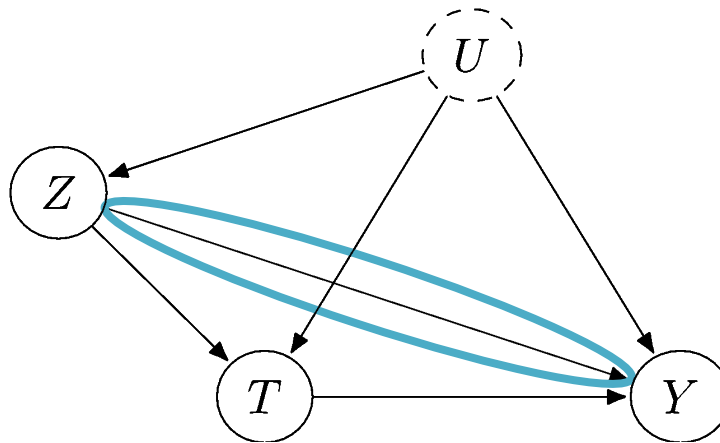


What is an Instrument?

(Slides adapted from Brady Neal's Introduction to Causal Inference class)

# Assumption 2: Exclusion Restriction

The causal effect of  $Z$  on  $Y$  is fully mediated by  $T$

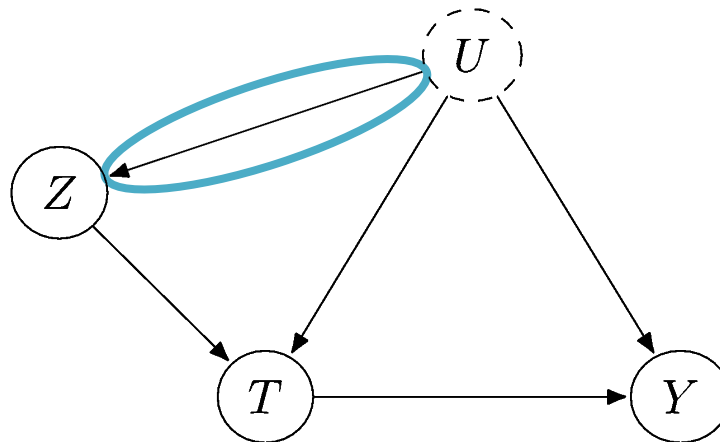


What is an Instrument?



# Assumption 3: Instrumental Unconfoundedness

$Z$  is unconfounded (in the setting of no  $X$ , this simply means  $U$  and  $Z$  are independent)



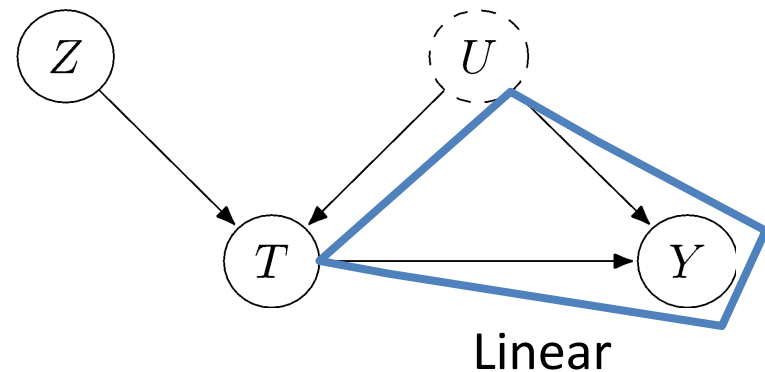
What is an Instrument?

# Warm-up: linear potential outcome, no $X$

Assume potential outcomes given by the linear model,

$$Y_t(U) = \alpha_u U + \delta \cdot t + \epsilon_t, \quad \mathbb{E}[\epsilon_t] = 0$$

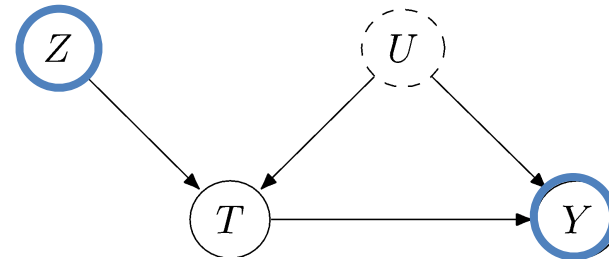
Z doesn't appear because of the exclusion restriction assumption



# Warm-up: linear potential outcome, no $X$

$$\begin{aligned} & \mathbb{E}[Y \mid Z = 1] - \mathbb{E}[Y \mid Z = 0] \\ &= \mathbb{E}[\delta T + \alpha_u U \mid Z = 1] - \mathbb{E}[\delta T + \alpha_u U \mid Z = 0] \quad (\text{exclusion restriction and linear outcome assumptions}) \\ &= \delta (\mathbb{E}[T \mid Z = 1] - \mathbb{E}[T \mid Z = 0]) + \alpha_u (\mathbb{E}[U \mid Z = 1] - \mathbb{E}[U \mid Z = 0]) \\ &= \delta (\mathbb{E}[T \mid Z = 1] - \mathbb{E}[T \mid Z = 0]) + \alpha_u (\mathbb{E}[U] - \mathbb{E}[U]) \quad (\text{instrumental unconfoundedness assumption}) \\ &= \delta (\mathbb{E}[T \mid Z = 1] - \mathbb{E}[T \mid Z = 0]) \end{aligned}$$

$$\delta = \frac{\mathbb{E}[Y \mid Z = 1] - \mathbb{E}[Y \mid Z = 0]}{\underbrace{\mathbb{E}[T \mid Z = 1] - \mathbb{E}[T \mid Z = 0]}}_{\text{(non-zero due to relevance assumption)}}$$

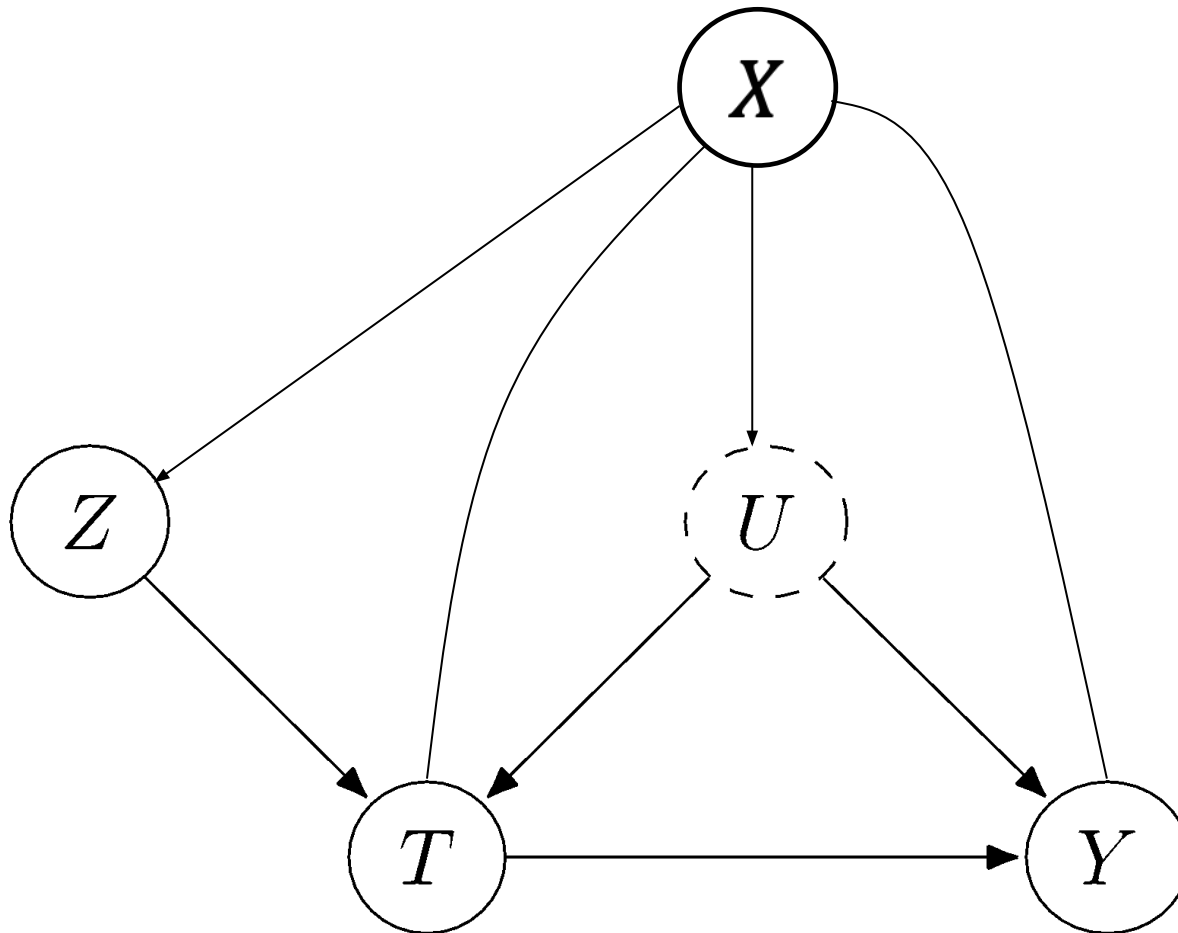


$$Y_t(U) = \alpha_u U + \delta \cdot t + \epsilon_t$$

# Estimation using (conditional) instruments

Assume potential outcomes given by:

$$Y_T(x, U) = \delta(x)T + g(x, U) + \epsilon_T$$



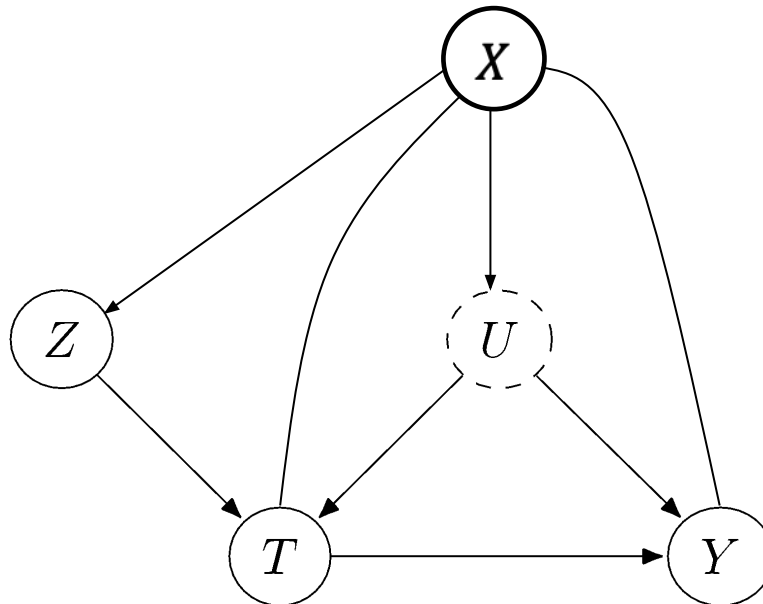
Goal: estimate  
 $\text{CATE}(x) = \delta(x)$

# Estimation using (conditional) instruments

Assume potential outcomes given by:

$$Y_T(x, U) = \delta(x)T + g(x, U) + \epsilon_T(x)$$

Theorem:  $\text{CATE}(x) = \delta(x) = \frac{\mathbb{E}[Y|Z = 1, x] - \mathbb{E}[Y|Z = 0, x]}{p(T = 1 | Z = 1, x) - p(T = 1 | Z = 0, x)}$



*Assume*  
 $\mathbb{E}[\epsilon_0 | x] = 0$   
 $\mathbb{E}[\epsilon_1 | x] = 0$

# Summary

- Close connection between causal inference and off-policy evaluation
- Same ideas can be used to evaluate dynamic treatment regimes when there are *multiple timepoints / actions*
- Instrumental variables can be used to estimate ATE and CATE when there is unobserved confounding

# References

- [Introduction to causal inference from a machine learning perspective](#) by Brady Neal, 2020.
  - Section 8.2: Sensitivity Analysis
  - Chapter 9: Instrumental Variables(See also the many references within for both recent literature and where these methods were originally introduced.)
- Syrgkanis et al., [Machine Learning Estimation of Heterogeneous Treatment Effects with Instruments](#), NeurIPS 2019.
- Boominathan et al., [Treatment Policy Learning in Multiobjective Settings with Fully Observed Outcomes](#), KDD 2020.

# Additional references

- Chakraborty & Moodie, [Statistical Methods for Dynamic Treatment Regimes: Reinforcement Learning, Causal Inference, and Personalized Medicine](#). Springer, 2013
- O. Gottesman, F. Johansson, M. Komorowski, A. Faisal, D. Sontag, F. Doshi-Velez, L. Celi. [Guidelines for reinforcement learning in healthcare](#). [Nature medicine](#), 2019
- Li et al., [G-Net: a Recurrent Network Approach to G-Computation for Counterfactual Prediction Under a Dynamic Treatment Regime](#). Proceedings of Machine Learning Research 158:282–297, 2021
- Hua, Mei, Zohar, Giral, Xu. [Personalized Dynamic Treatment Regimes in Continuous Time: A Bayesian Approach for Optimizing Clinical Decisions with Timing](#). Bayesian Analysis. Advance Publication, 1-30, 2021